Analysis of H-plane Circular Bend of Rectangular Waveguide based on Equivalent Multi-transmission Line Network Representation

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Abstract In order to calculate the wide-band frequency characteristics of the H-plane circular bend of rectangular waveguide with an arbitrary bend curvature including sharp bend and any bend angle, a systematic method based on planar circuit theory is proposed; equivalent multi-transmission line model are formulated and successfully applied to the practical structure, as well as E-plane circular bend case. [7]

1. Introduction

H-plane circular bend of the rectangular waveguide shown in Fig. 1, is an important waveguide component. However, so far obtained analytical method and its numerical results [1-5] are limited to the gradual bend case only. Therefore, analytical method and numerical data which can cover wide bend parameters (=bend curvature C and bend angle α which are explained in Fig. 1) including sharp bend are strongly needed not only for academic interest but also for the integration of microwave circuit.

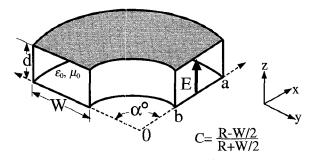
This paper treats the above problem based on the equivalent multi-transmission line network representation [6], which is derived from H-plane planar circuit equations [8]. Practically, how to calculate the network parameters is explained in general, based on planar circuit theory and then actual network parameters are calculated as a function of normalized frequency with bend curvature parameter C. Finally, based on these parameters, the frequency characteristics for right angle H-plane circular bend case is calculated for wide range of bend curvature as an example.

2. Equivalent multi-transmission line network representation

H- plane curved rectangular waveguide $(d \times W)$ can be considered to be a H-plane planar circuit as a whole, where field components and planar voltage/current are related by (B),(C),(D) in Table 1 [8].

Hence, the frequency characteristics of the curved rectangular waveguide shown in Fig.1 can be given by solving planar circuit equations (E,G) in Table 1 directly under the short circuited boundary condition (F) and TE10 dominant mode excitation condition.

Here, instead, the frequency characteristics are calculated based on the equivalent multi-transmission line network representation given in Fig. 2. This equivalent network representation is derived by the modal analysis of the planar circuit, appling the separation



$C = \frac{b}{a}$:bend curvature parameter

(R: average radius of the curved waveguide)
 Fig.1 H-plane α° circular bend of rectangular wave-guide and coordinate system

Field	$\mathbf{E}(0, E_z), \ \mathbf{H}(\mathbf{H}_t, 0)$	В
Field component	$E_z(x, y, z) = E_z(x, y)$ $\mathbf{H}_t(x, y, z) = \mathbf{H}_t(x, y)$	С
Electric Voltage Electric Current	$V^{E} = -E_{z}(x, y) \cdot d [V]$ $\mathbf{J}^{E} = \mathbf{H}_{t}(x, y) \times \mathbf{k} [A/m]$	D
Planar Circuit Equations with B. C.	$\begin{cases} \operatorname{grad} V^{\mathrm{E}} = -jX^{\mathrm{E}}\mathbf{J}^{\mathrm{E}} \\ \operatorname{div} \mathbf{J}^{\mathrm{E}} = -jB^{\mathrm{E}}\mathbf{V}^{\mathrm{E}} \end{cases}$	Е
	$V^{\rm E} = 0 (\text{or } \mathbf{J}^{\rm E} \times \mathbf{n} = 0)$	F
Planar Immittance	$X^{\mathrm{E}} = \omega \mu_0 d, \ B^{\mathrm{E}} = \frac{\omega \varepsilon_0}{d}$	G
propagation constant	$\beta_{i}^{E} = k_{\mathrm{o}} = \omega \sqrt{\varepsilon_{\mathrm{o}} \mu_{\mathrm{o}}}$	H

Table1H-plane planar circuit equations andthe relation between field components and planarvoltage/current with boundary condition.

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of variable technique to the planar circuit structure (Table 2 [6]).

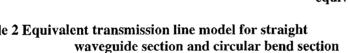
In the straight rectangular waveguide section (A, in Table 2), where 1-s-z coordinate system is defined, p-th mode voltage and current are given by (B₁), where p-th width mode $f_p^E(s)$ is also defind; modal voltage and modal current along ℓ , $V_{\rm p}(\ell)$ and $I_{\rm p}(\ell)$, are retated by the transmission line equations (C1) with p-th mode characteristic impedance $Z_{cp}^{\prime E}$ and propagation constant β_p^E .

In the curved rectangular waveguide section (A2 in Table 2), where $r \cdot \theta \cdot z$ coordinate system is defined, p-th mode voltage and current are given by (B2), where n-th radial mode function $R_n^E(r)$ is defined by (A) in Table 3; the modal voltage and modal current along θ , $V_n^E(\theta)$ and $I_n^E(\theta)$, are related by the transmission-line-like equations(C2) with n-th mode characteristic impedance Z_{cn}^{E} and circular (azimuthal) propagation constant v_n^E . The coupling between p-th mode in straight waveguide and n-th mode in the circular bend is defined by ideal transformer ratio and given by eq.(1)

$$\mathbf{n}_{n,p}^{(i)} = \frac{1}{W} \int_0^W f_p^E(s^{(i)}) R_n^E(r) ds^{(i)} \qquad (i = \#1, \ \#2)$$
(1)

Hence, the whole equivalent network becomes that in Fig.2. Also 2-port (input/output) mode impedance matrix is given by eq.(2)

$$\mathbf{Z}_{p,q}^{E} = \sum_{n=1}^{\infty} \begin{pmatrix} n_{np}^{(1)} & 0\\ 0 & n_{np}^{(2)} \end{pmatrix} \cdot \begin{pmatrix} Z_{cn}^{E} \operatorname{csch} j \boldsymbol{v}_{n} \boldsymbol{\alpha} & Z_{cn}^{E} \operatorname{csch} j \boldsymbol{v}_{n} \boldsymbol{\alpha} \\ Z_{cn}^{E} \operatorname{csch} j \boldsymbol{v}_{n} \boldsymbol{\alpha} & Z_{cn}^{E} \operatorname{csch} j \boldsymbol{v}_{n} \boldsymbol{\alpha} \end{pmatrix} \cdot \begin{pmatrix} n_{nq}^{(1)} & 0\\ 0 & n_{nq}^{(2)} \end{pmatrix}$$
(2)



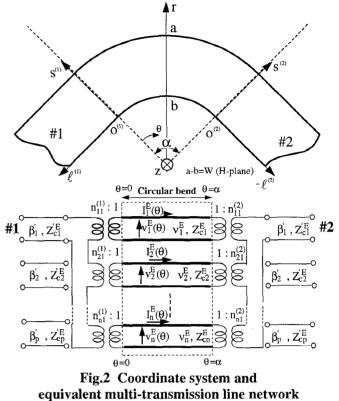
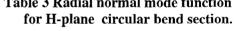


Table 3 Radial normal mode function



А

В

С

Straight waveguide (ℓ,s,z)		Circular bend (r, θ, z)		R_n^E : <i>n</i> -th radial normal mode	
waveguide straight section	A1	waveguide circular bend section	A2	$\frac{1}{r}\frac{d}{dr}\left(r\frac{dR_{n}^{E}}{dr}\right) + \left[\left(\beta_{t}^{E}\right)^{2} - \frac{\left(v_{t}^{E}\right)^{2}}{r^{2}}\right]R_{n}^{E} = 0$ $\beta_{t}^{E} = k_{0}$ B.C. $R_{n}^{E} = 0$ (r = a, b) $\int_{b}^{a}\frac{R_{m}^{E}(r)R_{n}^{E}(r)}{r}dr = \delta_{mn}$	
Separation of variable with <i>p</i> -th mode width function $f_p^E(s)$		Separation of variable with $R_n^E(r)$ <i>n</i> -th radial mode function		Analytical solution for $\beta_i^{\mathrm{E}}(=k_0)=0$	
$V_{p}^{E}(\ell,s) = V_{p}^{E}(\ell)f_{p}^{E}(s)$ $J_{\ell p}^{E}(\ell,s) = [I_{p}^{E}(\ell)/W]f_{p}^{E}(s)$ $J_{e p}^{E}(\ell,s) = j\frac{1}{X^{E}}V_{p}^{E}(\ell)f_{p}^{E}(s)$ $f_{p}^{E}(s) = \sqrt{2}\sin(p\pi s/W) (p = 1, 2, \cdots)$	Bı	$V_n^{\rm E}(r,\theta) = V_n^{\rm E}(\theta) \cdot R_n^{\rm E}(r)$ $J_{\theta_n}^{\rm E}(r,\theta) = I_n^{\rm E}(\theta) \cdot R_n^{\rm E}(r) / r$ $J_m^{\rm E}(r,\theta) = j \frac{1}{\chi^{\rm E}} V_n^{\rm E}(\theta) \cdot R_n^{\rm E}(r)$ $R_n^{\rm E}(r): \text{see Table 3} (n = 1, 2, \cdots)$	B2	$R_n^E(r) = \sqrt{-\frac{2}{\ln C}} \sin\left[\frac{n\pi}{\ln C}\ln\frac{r}{a}\right]$ $v_n^E = -j\frac{\pi}{\ln C}n (n = 1, 2,)$ $C = b/a$ Numerical solution for $\beta_t^E \neq 0$ by	
Transmission line equations along ℓ		Transmission line equations along $ heta$		non-uniform transmission line	
$\frac{dV_p^{\rm E}}{d\ell} = -jX_p^{\rm E}I_p^{\rm E} , X_p^{\rm E} = \frac{X^{\rm E}}{W}$ $\frac{dI_p^{\rm E}}{d\ell} = -jB_p^{\rm E}V_p^{\rm E} , B_p^{\rm E} = \frac{(\beta_p^{\rm E})^2}{X^{\rm E}} W$ $Z_{cp}^{\rm E} = \frac{X^{\rm E}}{\beta_p^{\rm E}W} = \frac{\omega\mu_0 d}{\beta_p^{\rm E}W}$ $\beta_p^{\rm E} = \sqrt{k_0^2 - (p\pi/W)^2}$	C1	$\frac{dV_n^{\rm E}}{d\theta} = -jX^{\rm E}I_n^{\rm E}$ $\frac{dI_n^{\rm E}}{d\theta} = -j\frac{(v_n^{\rm E})^2}{X^{\rm E}}V_n^{\rm E}$ $v_n^{\rm E}: \text{ circular propagation constant}$ $Z_{cn}^{\rm E} = \frac{X^{\rm E}}{v_n^{\rm E}}$	C2	$\upsilon(r) = R_n^{\rm E}(r) , \ i(r) = jr \cdot \frac{dR_n^{\rm E}}{dr}$ $\begin{cases} \frac{d\upsilon}{dr} = -jx(r) \ i(r) \\ \frac{di}{dr} = -jb(r) \ \upsilon(r) \end{cases}$ $x = 1/r , \ b = k_0^2 \ r - \nu^2 / r$ B.C. $\upsilon(r) = 0 \ (r = a, b)$	
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Table 2 Equivalent transmission line model for straight

3. Calculation of radial normal mode function

The key step in this analysis is the calculation of radial normal mode function $R_n^E(r)$ and circular propagation constant v_n^E defined by (A) in Table 3 as function of operating frequency (or $\beta_t = k_0$) and bend curvature parameter C. How to calculate them is explained in the following. When mode voltage and mode current along r are defined in such away as (C) in Table 3, the second order differential equation (A) in Table 3 can be transformed to a nonuniform transmission line equations given by (C) in Table 3.

In order to calculate R_n^E and v_n^E numerically for a given $\beta_i = k_0$ or frequency, this non-uniform transmission line between b and a is approximated by cascade connection of infinitesimally small uniform transmission line section as shown in Fig. 3. In our present case, waveguide width W (=*a*-*b*) is equally divided into N sections ; position dependent original reactance x and susceptance b given by (C) in Table3 are approximated to be the corresponding constant value at the center position of each section, respectively. Then, the corresponding eigenvalue problem is solved by the following way. Assuming v, F-matrix of each uniform section \mathbf{F}_i can be easily calculated. Therefore, Total F-matrix between port b and port a is given by their cascade product and can be expressed by eq. (3)

$$\begin{pmatrix} \boldsymbol{\upsilon}_b \\ \boldsymbol{i}_b \end{pmatrix} = \mathbf{F}_1 \cdot \mathbf{F}_2 \cdot \dots \cdot \mathbf{F}_N \begin{pmatrix} \boldsymbol{\upsilon}_a \\ \boldsymbol{i}_a \end{pmatrix} = \begin{pmatrix} A_i & B_i \\ C_i & D_i \end{pmatrix} \begin{pmatrix} \boldsymbol{\upsilon}_a \\ \boldsymbol{i}_a \end{pmatrix}$$
(3)

Numerical search of v_n^E , which makes $B_i = 0$, gives v_n^E and then $R_n^E(r)$. Thus calculated circular propagation constants v_n^E vs normalized frequency for wide range of curvature parameter *C* are shown in Figs.4 and 5, where the normalized frequency is defined as $F=2W/\lambda_0$ (λ_0 =free space wavelength). Also radial normal mode functions of lower order are shown in Figs. 4 and 5. Through these calculation N is taken as 200 or above this value. Analytical solution for F=0.0 ($\beta_i=0$) is exactly given by (B) in Table 3, which is practically outside desired frequency band but is used for demonstrating the validity of the present numerical analysis.

4. Frequency characteristics of right angle circular bend

Once the $R_n^E(r, C, F)$ are obtained, the ideal transformer ratio n_{np} defined by eq.(1) are easily calculated; some calculated results are shown in Figs.4 and 5 for p=1. By these calculation, the required network parameters of the equivalent multi-transmission line in Fig. 2 are prepared. Therefore, using these network parameters, frequency characteristics of circular bend can be calculated for any bend angle and bend curvature. As an example, frequency characteristic of the VSWR for the right-angle circular bend case are calculated and shown in Fig. 6 with curvature C as a parameter.

5. Conclusion

Analytical method which can calculates input/output performance of H-plane circular bend structure is explained based on the equivalent multi-transmission line network representation and applied to the practical structure. Wide band frequency characteristics for right angle circular bend case are calculated as an example for wide range of curvature parameter. 775

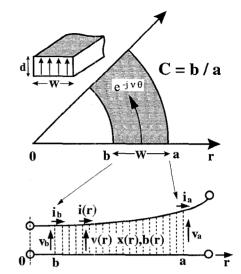


Fig.3 Non-uniform transmission line model and its step-like approximation

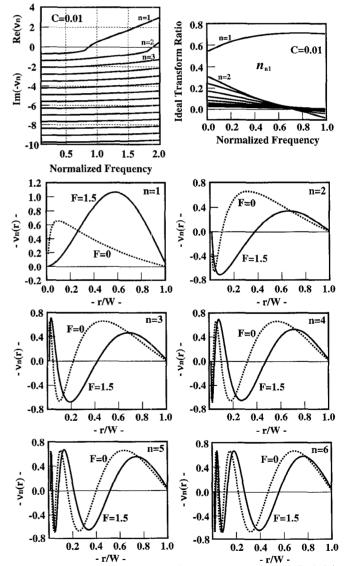


Fig.4 Example of numerical computation for C=0.01based on F-matrix; circular propagation constant, the corresponding radial mode function at F=0.0 and F=1.5 and the ideal transform ratio n_{n1}

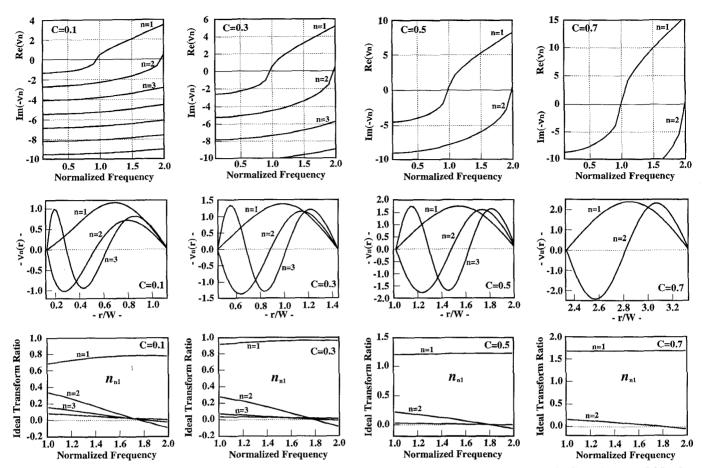


Fig.5 Circular propagation constant $v_n(F,C)$, radial mode function of lower mode $V_n=R_n(r,C,F=1.5)$ and ideal transformer ratio between *n*-th radial mode and TE₁₀ mode (*n*=*n*_{n1}), where curvature parameter *C* are taken as 0.1, 0.3, 0.5 and 0.7 and normalized frequency *F* is defined by $2W/\lambda_0$. (λ_0 =free space wavelength)

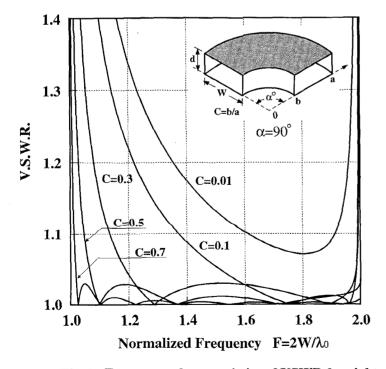


Fig.6 Frequency characteristics of VSWR for right angle H-plane circular bend with bend curvature parameter C.

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